#### WARNING



- This switch is designed for general industrial use, not for use as a safety device.
- Do not connect this device to AC power. Doing so may cause rupture or burnout.

#### Handling Precautions

- This device is a precision instrument. Do not hit it or bump it against any object.
- The diameter of the mounting bracket holes must be 4 mm or less. Tighten the mounting screws to a maximum torque of 0.8 N·m.
- Up to 100 ms is required for stabilization after the power is turned on.
- For outdoor use, prevent direct exposure to sunlight and rainwater.
- Do not allow water, cutting oil, etc., to splash on the device or the cables.
- Do not expose the device to chemicals (organic solvents, acids, alkalis).
- If the lens is dirty, wipe it with a soft, damp, clean cloth. Do not use an organic solvent like alcohol.
- · Switches cannot be connected in series (AND circuit). Parallel connection (OR circuit) is supported.

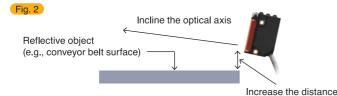
#### Wiring Precautions

- · Bends in the cable should have a radius of at least 15 mm (30 mm min. for the section immediately next to the device).
- · Avoid use in which the cable receives repeated bending stress.
- Do not pull the cable with excessive force (≥ 50 N). Doing so might cause disconnection, resulting in a short circuit and burnout.
- Tighten connectors firmly by hand.
- If extension of the cable is necessary, use at least 0.3 mm<sup>2</sup> wire, no more than 100 m long.
- · Special care is required at low temperatures (below 0 °C), because cables become stiff and flexibility is much lower.
- · When using an inverter or servo motor, be sure to ground the frame ground terminal and ground terminal.
- Do not put the wires of the photoelectric switch and motor power lines or other power wires in the same conduit. Doing so may cause malfunction or damage due to induction noise. Route the wires separately or put them in a different conduit.

#### Installation Precautions

- Install the device so that the target object moves in the direction shown in Fig. 1. If the switch is installed horizontally, false detection of an object that is situated away from the set distance may result. In this case, the use of a shielding plate is recommended. If it is not possible to install a shielding plate, thoroughly check device operation before use.
- If a mirrorlike or reflective object is located near the device, unreliable detection may occur. In this case, increase the distance between the device and the reflective object, or incline the optical axis as shown in Fig. 2.
- Depending on the shape or pattern of the object, unreliable detection may occur. Before use, thoroughly check device operation.
- If the background or the target object is reflective, incline the optical axis so that the device does not receive the reflected light directly.

## Recommended shielding plate Conveyor belt Conveyor belt Check operation under actual conditions



#### Disposal Precautions

• When discarding the product, dispose of it as industrial waste, following local regulations.

Please read "Terms and Conditions" from the following URL before ordering and use.  $\label{eq:conditions} % \begin{subarray}{ll} \end{subarray} %$ 

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#### **Azbil Corporation**

Advanced Automation Company

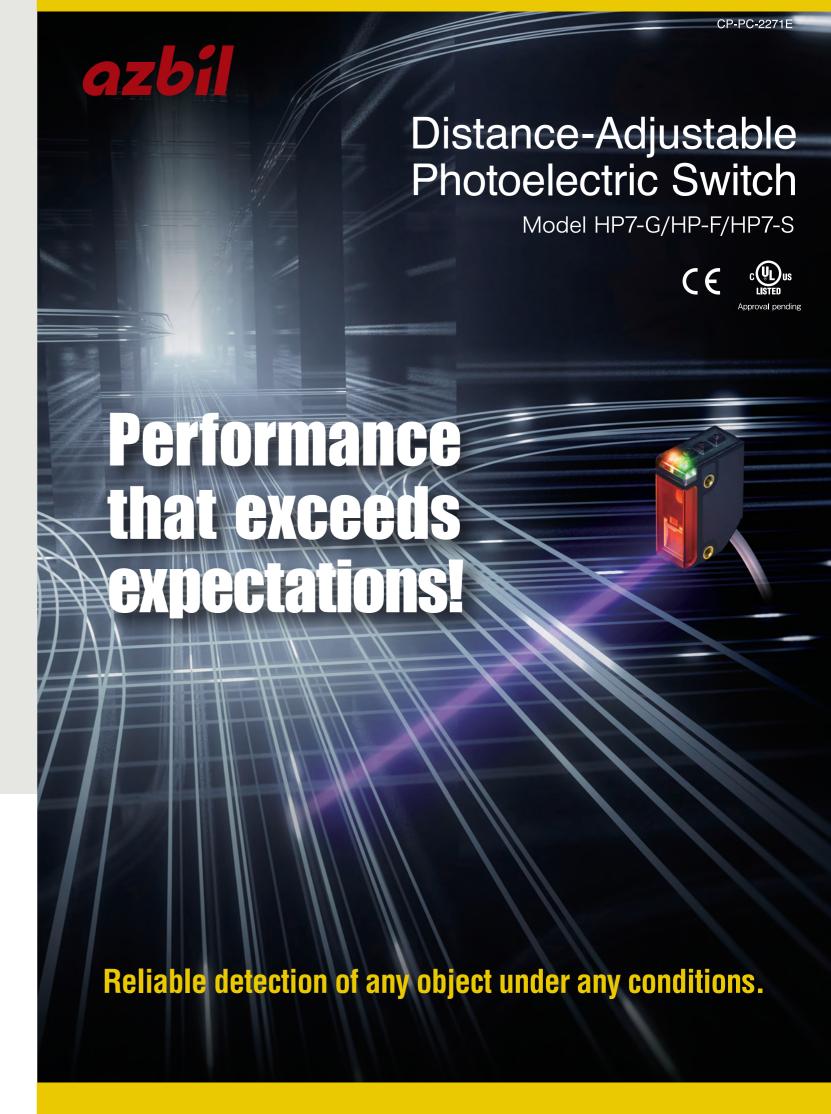
Yamatake Corporation changed its name to Azbil Corporation on April 1, 2012.

1-12-2 Kawana, Fujisawa Kanagawa 251-8522 Japan

URL: https://www.azbil.com

1st Edition : Feb. 2018-SK 3rd Edition : Oct. 2019-SK

CP-PC-2271E



### Compact size with super long-distance detection

Thanks to the triangulation method, objects of any color made from any material can be reliably detected. With long-distance detection of up to 750 mm, switch is suitable for use on conveyor lines.

#### **Achieves formerly impossible performance**

#### Compact & super range

3× the distance

Background Suppression type: 750 mm

Foreground Suppression type: **500** mm



#### **Excellent basic characteristics**

#### **Detection performance**

The use of triangulation and an infrared light source reduces detection distance variation resulting from differences in object color and material. Capable of detecting small differences.

#### **Temperature characteristics**

Variation in sensing distance over full operating temperature range (-30 to +55 °C) is  $\pm 4$  % max. (reference value when HP7-G81 is set to 500 mm).

#### Resistance to LED lighting and ambient light

Uses a new algorithm and a filter that cuts light from ambient illumination.

#### Angle characteristics

Variation in sensing distance in the horizontal direction with a  $45^{\circ}$  incline:  $\pm 2\%$  max. (reference value when HP7-G81 is set to 500 mm)

#### Designed for ease of use



# Metal threads Metal screw threads improve workability by preventing stripping. Higher tightening strength (x 1.6\*) prevents cracking of housing. \*Compared to our resin threads (0.5 N·m)



#### LINEUP \_\_\_\_\_

#### Three available models optimized for different purposes

**High-performance model HP7-G\_**Background Suppression

- Super-long 750-mm sensing distance
   Ability to tune and adjust allows detection of various types of objects
- High-resolution, high-precision model HP7-F\_\_ Foreground Suppression
- Excellent step difference detection
   Two types, with sensing distances

of 500 and 250 mm

- Zone detection model HP7-S\_\_ Background suppression (fixed distance)
- Sensing distance is adjusted at the factory
- Background suppression function is easier to use



**Long-distance detection** 

Reliable detection

Adjustment is not required

1

#### Background suppression high-performance model

Molde HP7-G\_\_

Compact, but capable of long-distance detection (to 750 mm). The automatic tuning and adjustment functions allow detection of various types of objects under various installation conditions.

#### >>> Can reliably detect multiple objects of various colors made from various materials.



Various types of corrugated cardboard cartons Reliably detects corrugated cardboard cartons of various

colors with various types of marking.



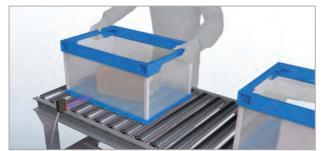
Reused pallets

Reliably detects dirty pallets of various colors.

#### >>> Useful for locations where reflectors cannot be installed.



L-shape conveyors (direction converters and loaders) The 750-mm sensing distance covers the width of the conveyor belt, simplifying switch layout.



Inspection and carry lines Reliable detection of the target only, not the worker.

#### >>> Long-distance models can be located away from the target.



Between conveyor belts Simplifies switch layout.



Objects of various heights Detects objects of various thicknesses.

#### >>> Approaching objects can be stopped at the desired position.



Can decelerate and stop moving racks Large sensors are not required. Automatic tuning reduces setup time.



L-shape conveyors (direction converters and loaders) Since detection does not rely on color or material, it is possible to stop objects at the same position.

#### Foreground suppression high-resolution, high-precision model

Molde HP7-F\_\_

In addition to detecting small step differences, this model can reliably detect reflective objects.

#### >>> Detects thin objects



#### >>> Detects reflective objects



Note: For use only with a stable background (conveyor belt, etc.).

#### Background suppression (fixed distance) zone detection model Molde HP7-S\_

Background suppression function is easier to use. Sensing distance is adjusted at the factory. Onsite adjustment is not required.

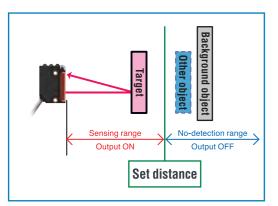
#### >>> Circuit board transport



#### >>> Detection at the bottom layer only of multi-layer conveyor belts



#### Background Suppression (Normally Open operation)



#### Detection function is based on the distance to the target object.

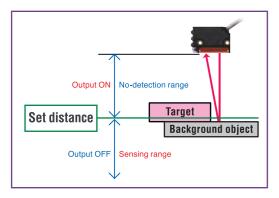
Background objects beyond the set distance are not detected.

In the figure on the left, the background and other (potentially interfering) object are not detected.

#### Note

Detection may not be reliable for objects with very low reflectivity or for reflective objects.

#### Foreground suppression function (Normally Open operation)



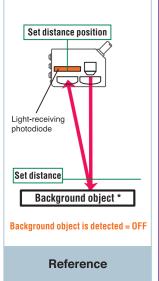
#### Detection function is based on the distance to the background object.

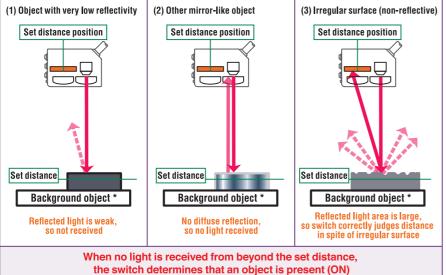
Effective when there is a conveyor belt or other stable background.

Enables detection of objects that cannot be detected reliably by background suppression (i.e., reflective or low reflectivity objects)

Suitable for detecting small step differences.

Behavior The switch determines that a target object is present when the background object cannot be detected





\* e.g., conveyor belt

Note

Can be used only when there is a background object

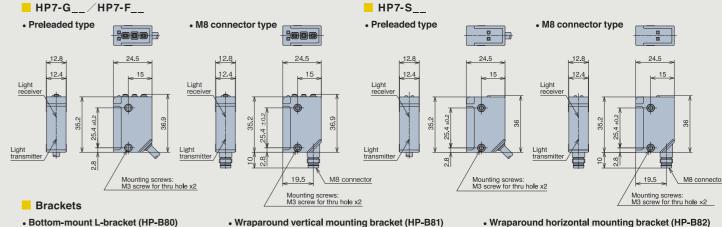
#### **Table of models**

Туре	Appearance	Detection method	Max. sensing distance	Light source	Output	Model No.
		Background	750 mm		NPN/NO	HP7-G81
		Suppression			PNP/NO	HP7-G82
			250 mm		NPN/NO	HP7-F21
		Foreground			PNP/NO	HP7-F22
Distance- adjustable	Suppression	500 mm	Infrared	NPN/NO	HP7-F41	
				PNP/NO	HP7-F42	
diffuse scan			100 mm	Illitated	NPN/NO	HP7-S11
	Zone detection background suppression (fixed distance)	100 11111		PNP/NO	HP7-S12	
		200		NPN/NO	HP7-S31	
			300 mm		PNP/NO	HP7-S32

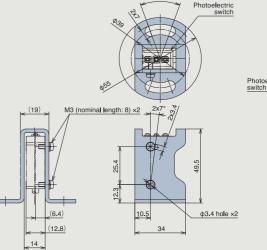
Item	Appearance	Description	Compatible models	Model No.
Standard bracket		Bottom-mount L-bracket		HP-B80
Wraparound		Wraparound vertical mounting bracket	HP7-G HP7-F HP7-S	HP-B81
bracket		Wraparound horizontal mounting bracket	11170	HP-B82

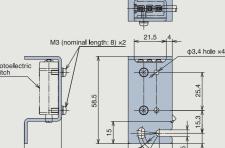
#### **External dimensions**

(Unit: mm)



# Photoelectric switch Sw





#### **Specifications**

Туре			Dista	nce measurement diffuse	scan	
Torrigal and dal No.	NPN	HP7-G81	HP7-F21	HP7-F41	HP7-S11 / HP7-S13	HP7-S31 / HP7-S33
Typical model No.	PNP	HP7-G82	HP7-F22	HP7-F42	HP7-S12 / HP7-S14	HP7-S32 / HP7-S34
Detection method		Background Suppression Foreground Suppression		Zone detection Background Suppression (fixed distance)		
Distance setting me	ethod	Tuning: [Center] t	outton. Adjustment: [Far] ar	nd [Near] buttons	No	ne
Power			DC 1	0.2 to 26.4 V (ripple: 10 % r	max.)	
Current consumption	n			20 mA max.		
Distance setting rar (target: white paper		100 to 750 mm	100 to 250 mm	200 to 500 mm	_	_
Sensing range (target: white paper	) *5	From 5 mm to set distance (Set distance: 300 mm min.) From about 32 mm to set distance (Set distance: less than 300 mm)	From 5 mm to set distance (Set distance: 150 mm min.) From about 30 mm to set distance (Set distance: less than 150 mm)	From 5 mm to set distance (Set distance: 300 mm min.) From about 25 mm to set distance (Set distance: less than 300 mm)	Approx. 27 to 100 mm	Approx. 5 to 300 mm
Hysteresis (target: white paper	) *5	When set distance is 750 mm: 8 % max.	When set distance is 250 mm: 0.8 % max.	When set distance is 500 mm: 4 % max.	2 %	max.
Operation modes		N.O. and N.	C. can be switched by butto	on operation		□2: N.O. operation □4: N.C. operation
Output modes	*1			NPN/PNP open collector		
Control output		Switching current: for preleaded and preleaded connector types 100 mA (resistive load), for M8 connector type 50 mA (resistive load) Output withstand voltage: 30 V Residual voltage: 1 V or less				50 mA (resistive load)
Response time	*2	1 msec 0.7 msec				nsec
Light source		Infrared (wavelength: approx. 860 nm)				
Indicators	*3	Operation indicator (orange) Reliability indicator (green) Operation indicator (orange) Power indicator (green)		Operation indicator (orange) Reliability indicator (green)		
Ambient light intens	sity	Incandescent light: 10,000 lx max. Sunlight: 40,000 lx max. *4				
Operating temperat	ure	For preleaded and preleaded connector types –30 to +55 °C, for M8 connector type –30 to +50 °C (without freezing or condensation)				
Insulation resistanc	e			20 $M\Omega$ min. (at DC 500 V)		
Withstand voltage			AC 1,000 V 50/60 Hz for	one minute between electri	cally live metal and case	
Vibration resistance	e	1	0 to 55 Hz, 1.5 mm peak-to	-peak amplitude, 2 hours e	ach in X, Y, and Z direction	S
Shock resistance			500 m/s <sup>2</sup> 1	0 times each in X, Y, and Z	directions	
Protective structure				IP67 (IEC standard)		
Wiring method		HP7: preleaded 2 m. HP7L050: preleaded 5 m. HP7C003: M12 preleaded connector, 30 cm. HP7T: M8 connector.				
Circuit protection		Error prevention	on circuit at power on (100	ms max.), power miswiring	protection, output short-cir	cuit protection
Mutual interference pro	tection			Up to 2 units		
			may be langur if offeeted by ligh			

- \*1. FETs are used for output components. \*2. Response time may be longer if affected by light from other switches.
- \*3. For indicator functions see p. 9. \*4. HP7-G8\_/HP7-F4\_: illuminance at lens surface (incidence angle: 15° min.); HP7-F2\_/HP7-S1\_/HP7-S3\_: illuminance of target object
- \*5. It changes with set distance. Please refer to graph of characteristic (typical example).

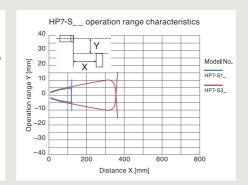
7

#### Output operation Output stage circuit Note: The relationship between the presence/absence of an object and the output is the same for both detection methods. Background object Background Suppression Brown Load Control output Black DC **NPN** output 10.2 100/50 mA max. type to 26.4V Main Set distance circuit Blue Foreground Suppression Brown Set distance Target 100/50 mA max. Main DC **PNP** output Black Background object circuit 10.2 to 26.4V type Control output Load Output Target object Blue

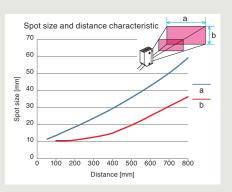
#### **Typical characteristics**

#### **Operation range characteristics**

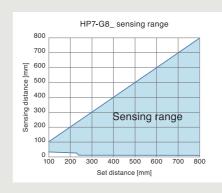
### HP7-G8\_ operation range characteristics Distance X [mm]

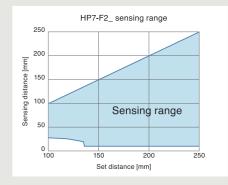


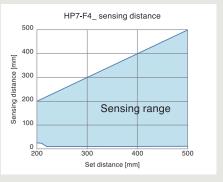
#### Spot size and distance characteristic



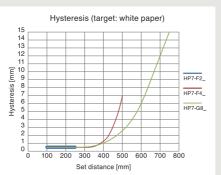
#### Sensing range



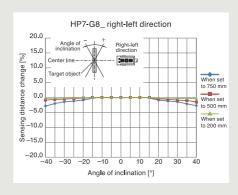


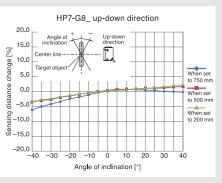


#### Hysteresis and distance characteristic

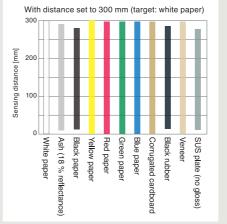


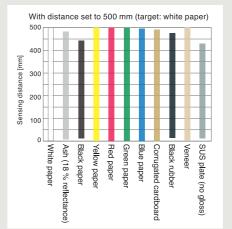
#### **Inclination characteristics**

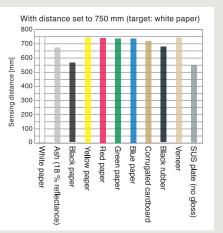




#### Graphs of sensing distance by object type







The above characteristics are typical examples only, not guaranteed values. Always test first under actual conditions and allow a margin for error.

ON

OFF OFF

ON

Yes

N.O.

N.C.

#### Names of parts

#### Green indicator Orange indicator [Far] button (+) [Center] button (C) [Near] button (-)

#### Indicator status

Indicator	During normal operation		During tuning	
Indicator	HP7-G	HP7-F	During turing	
Green indicator	Lit when detection is reliable	Always on	Blinks to indicate guidance	
Orange indicator	Lit when ou	Lit when output is ON		

#### Operation process flow: Relevant operation procedures



**Operation procedures** Note: The key lock is enabled when the device is turned on.

#### **STEP 1** Disabling and setting the key lock

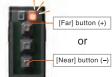
Disabling the key lock Turn the key lock off.



Hold down the [Far] or [Near] button until the green LED starts to blink slowly (approx. 3 seconds).

The green LED blinks slowly (at approx. 1 Hz) when keys are unlocked.

Enabling the key lock To enable the key lock, turn the power off and back on, or do the following.



Hold down the [Far] or [Near] button until the orange LED starts to blink slowly (approx. 3 seconds).

The orange LED blinks slowly (at approx. 1 Hz) when the keys are locked.

#### Checking the N.O./N.C. setting

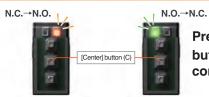


Press [Center] button 3 times consecutively

Orange LED blinks rapidly Green LED blinks rapidly (at approx. 10 Hz)

(at approx. 10 Hz)

#### Switching between N.O. and N.C.



Press [Center] button 5 times consecutively

Orange LED blinks rapidly Green LED blinks rapidly

#### **Restoring default settings**

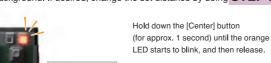
Factory default settings for set distance and N.O./N.C. can be restored.



Hold down the [Center] button until the green LED starts to blink rapidly (approx. 5 seconds) (at approx. 10 Hz).

Green LED blinks rapidly (at approx. 10 Hz)

#### STEP 2 Tuning (Model HP7-G\_\_) After adjusting the optical axis, tune the device. The set distance (OP) is automatically adjusted based on the state of the target object and background. If desired, change the set distance by doing **STEP 3**.



Orange LED blinks rapidly [Center] button (C) (at approx. 10 Hz)

The device goes into tuning mode



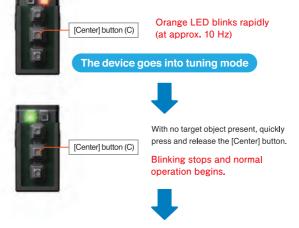
The orange and green LEDs blink rapidly (at approx. 10 Hz).



Setup is complete

#### STEP 2 Tuning (Model HP7-F\_\_)

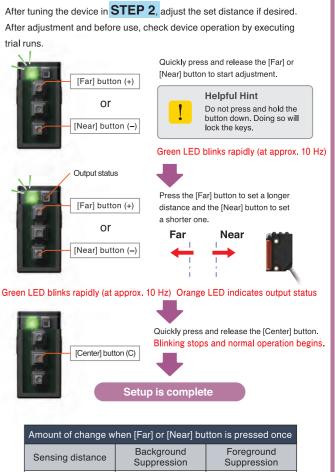
After adjusting the optical axis, tune the device. The set distance (OP) is automatically adjusted based on the distance to the background. The set distance after tuning varies depending on the distance to the background. It is set slightly in front of the background (by 2 to 15 mm). If desired, change the set distance by doing **STEP 3**.



Setup is complete



STEP 3 Adjustment

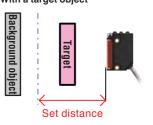


Amount of change when [Far] or [Near] button is pressed once				
Sensing distance	Background Suppression	Foreground Suppression		
250 mm	Approx. 2.5 mm	Approx. 0.5 mm		
500 mm	Approx. 5 mm	Approx. 1.5 mm		
750 mm	Approx. 15 mm			

#### Output operation (N.O./N.C.)

The relationship between N.O./N.C. setting and output operation is shown below.

With a target object



 Without target object Set distance

Setting	Target object	Output
N.O.	Yes	ON
	No	OFF
N.C.	Yes	OFF
	No	ON

	40 30 20 10	Sensing by Guidelight	
7	-10 0 250 Distance [m	500 750 m]	
approxin - If the gui	n cannot depict exact number ate reference. de light is hard to see, darken get object like white paper.		

10